

Adaptability, interpretability and rule weights in fuzzy rule-based systems

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Blended antilock braking system control method for all-wheel drive electric sport utility vehicle

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Condition monitoring of a Cartesian robot with a mechanically damaged gear to create a fuzzy logic control and diagnosis algorithm

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Design and experimentation of fuzzy logic control for an anti-lock braking system

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Utilizing the fuzzy logic algorithm for cartesian robot control system in conditions of mechanical damage transmission

