

A flapped paddle-fin for improving underwater propulsive efficiency of oscillatory actuation

Simha, Ashutosh; Gkliva, Roza; Kotta, Ülle; Kruusmaa, Maarja IEEE robotics and automation letters 2020 / p. 3176-3181

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The ARROWS project : adapting and developing robotics technologies for underwater archaeology

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2D estimation of velocity relative to water and tidal currents based on differential pressure for autonomous underwater vehicles

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