

Control of radial increment and winding density of composite cylindrical shells

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Design and experimentation of fuzzy logic control for an anti-lock braking system

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A model-based adaptive control of an autonomous driving car for lane change maneuver

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A model-based adaptive control of turning maneuver for catamaran autonomous surface vessel

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Spatial representation of self-driving vehicle for virtual entity of digital twin

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Wind force model and adaptive control of catamaran model sailboat

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