

Autonomous mobile robots for production logistics: a process optimization model modification
Raamets, Tõnis; Majak, Jüri; Karjust, Kristo; Mahmood, Kashif; Hermaste, Aigar Proceedings of the Estonian Academy of Sciences 2024 / p. 134-141 : ill <https://doi.org/10.3176/proc.2024.2.06>

Control of autonomous mobile robots using wireless network and MATLAB
Vu, Trieu Minh; Tamre, Mart; Hudjakov, Robert; Shvarts, Dmitry; Põlder, Ahti; Hiiemaa, Maito; Juurma, Märt Proceedings of the 11th International Conference of DAAAM Baltic Industrial Engineering : 20-22th April 2016, Tallinn, Estonia 2016 / p. 235-240 : ill <http://innomet.ttu.ee/daaam/>

Implementation of integrated wireless network and MATLAB system to control autonomous mobile robot
Tamre, Mart; Hudjakov, Robert; Shvarts, Dmitry; Põlder, Ahti; Hiiemaa, Maito; Juurma, Märt International Journal of Innovative Technology and Interdisciplinary Sciences : IJTIS 2018 / p. 18-25 : ill <https://doi.org/10.15157/IJTIS.2018.1.1.18-25>

Planning and acquisition of real-time production data through the virtual factory in chemical industry
Raamets, Tõnis; Karjust, Kristo; Hermaste, Aigar; Mahmood, Kashif ASME 2021 International Mechanical Engineering Congress and Exposition 2021 / paper no: IMECE2021-73080, 9 p <https://doi.org/10.1115/IMECE2021-73080>