

Event-based control for differentially flat systems: application to autonomous underwater vehicle
Kaldmäe, Arvo; Kotta, Ülle; Meurer, Christian; Simha, Ashutosh IFAC-PapersOnLine 2019 / p. 180-185
<https://doi.org/10.1016/j.ifacol.2019.11.775> [Conference proceedings at Scopus](#) [Article at Scopus](#) [Article at WOS](#)