

A model-based adaptive control of an autonomous driving car for lane change maneuver

Astrov, Igor; Udal, Andres; Jaanus, Martin 2021 44th International Convention on Information, Communication and Electronic Technology (MIPRO), September 27 - October 1, 2021, Opatija, Croatia : proceedings 2021 / p. 1330-1335 : ill
<http://www.mipro.hr/LinkClick.aspx?fileticket=RAMnkK6T5UQ%3d&tabid=196&language=hr-HR>
<https://doi.org/10.23919/MIPRO52101.2021.9597195>

A model-based control of self-driving car trajectory for lanes change maneuver in a smart city

Astrov, Igor WSEAS transactions on systems and control 2023 / art. 36, p. 346-353 : ill <https://doi.org/10.37394/23203.2023.18.36>
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A model-based LQR control of an obstacle avoidance maneuver of a self-driving car

Astrov, Igor; Udal, Andres; Pikner, Heiko; Malayjerdi, Ehsan 2022 IEEE 20th Jubilee World Symposium on Applied Machine Intelligence and Informatics (SAMI) : Poprad, Slovakia, 2-5 March 2022 2022 / p. 473-478 : ill
<https://doi.org/10.1109/SAMI54271.2022.9780755>