

A distributed model of ionomeric polymer metal composite

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Dynamical variation of the impedance of IPMC

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Electrode reactions in Cu-Pt coated Nafion[r] actuators

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Fractional-order modeling and control of ionic polymer-metal composite actuator

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A linked manipulator with ion-polymer metal composite (IPMC) joints for soft- and micromanipulation

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Towards a biomimetic EAP robot

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