

Axial displacements in ball screw mechanisms with two and four contact-point

Penkov, Igor; Aleksandrov, Dmitri International review of mechanical engineering 2011 / p. 1213-1218

https://www.researchgate.net/publication/289762576_Axial_displacements_in_ball_screw_mechanisms_with_two_and_four_contact-point

Efficiency optimization of mini unmanned multicopter

Penkov, Igor; Aleksandrov, Dmitri International review of aerospace engineering 2017 / p. 277-281 : ill

<https://doi.org/10.15866/irease.v10i5.12132>

Energy consumption of mini UAV helicopters with different number of rotors

Aleksandrov, Dmitri; Penkov, Igor 11th International Symposium "Topical Problems in the Field of Electrical and Power Engineering."

Doctoral School of Energy and Geotechnology II : Pärnu, Estonia, January 16-21, 2012 2012 / p. 259-262 : ill

Energy saving types of mini unmanned aerial vehicles

Aleksandrov, Dmitri; Penkov, Igor 9th International Symposium "Topical problems in the field of electrical and power engineering".

Doctoral school of energy and geotechnology. II : Pärnu, Estonia, June 14-19, 2010 2010 / p. 117-120 : ill

Fluid flow optimization on semiautomatic code marker base

Aleksandrov, Dmitri; Penkov, Igor 8th International Symposium "Topical Problems in the Field of Electrical and Power Engineering" : Doctoral School of Energy and Geotechnology. II : [Pärnu, January 11-16, 2010 : proceedings] 2010 / p. 306-308 : ill

Fluid flow optimization on semiautomatic code marker base

Aleksandrov, Dmitri; Penkov, Igor Journal of energy and power engineering 2012 / p. 916-920 : ill

Increasing of power characteristics of mini UAV helicopter by changing of its geometrical parameters

Aleksandrov, Dmitri; Penkov, Igor Machines, technologies, materials : [virtual journal] 2012 / p. 30-32 : ill

Influence of nozzle geometry on fluid flow parameters

Penkov, Igor; Aleksandrov, Dmitri International journal of applied mechanics and engineering 2020 / p. 215-222 : ill

<https://doi.org/10.2478/ijame-2020-0060> Journal metrics at Scopus Article at Scopus

Light-weight multicopter structural design for energy saving = Kergklassi multikopteri energiatarbe vähendamise konstruktsioonilised lahendused

Aleksandrov, Dmitri 2013 http://www.ester.ee/record=b2994326*est

Optimal gap distance between rotors of mini quadrotor helicopter

Aleksandrov, Dmitri; Penkov, Igor Proceedings of the 8th International Conference of DAAAM Baltic Industrial Engineering, 19-

21st April 2012, Tallinn, Estonia. 1 2012 / p. 251-255 : ill

Optimization mini unmanned helicopter energy consumption by changing geometrical parameters of coaxial rotor pairs

Aleksandrov, Dmitri; Penkov, Igor 12th International Symposium "Topical Problems in the Field of Electrical and Power Engineering."

Doctoral School of Energy and Geotechnology II : Kuressaare, Estonia, June 11-16, 2012 2012 / p. 139-141 : ill

Optimization of lift force of mini quadrotor helicopter by changing of gap size between rotors

Aleksandrov, Dmitri; Penkov, Igor Mechatronic systems and materials IV 2013 / p. 226-231 : ill

Propeller shrouding influence on lift force of mini unmanned quadcopter

Penkov, Igor; Aleksandrov, Dmitri International journal of automotive and mechanical engineering 2017 / p. 4486-4495 : ill

<https://doi.org/10.15282/ijame.14.3.2017.7.0354>

Rotor lifting force optimization by changing dimensions of rim around it

Aleksandrov, Dmitri; Penkov, Igor 13th International Symposium "Topical Problems in the Field of Electrical and Power Engineering."

Doctoral School of Energy and Geotechnology II : Pärnu, Estonia, January 14-19, 2013 2013 / p. 292-295 : ill