

Realization of nonlinear input-output equations in controller canonical form

Kaldmäe, Arvo; Kotta, Ülle Kybernetika 2018 / p. 736-747 <https://doi.org/10.14736/kyb-2018-4-0736> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Relaxing realizability conditions for discrete-time nonlinear systems

Kotta, Ülle; Schlahter, Kurt; Tönso, Maris Automatica 2015 / p. 67-71 <https://doi.org/10.1016/j.automatica.2015.05.007> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

A 6D space framework for the description of distributed systems

Pettai, Elmo Estonian journal of engineering 2012 / p. 140-171 : ill

State-space realization of nonlinear control systems : unification and extension via pseudo-linear algebra

Belikov, Juri; Kotta, Ülle; Tönso, Maris Kybernetika 2012 / p. 1100-1113 https://www.researchgate.net/publication/269024076_State-space_realization_of_nonlinear_control_systems_Unification_and_extension_via_pseudo-linear_algebra