

Development of digital twin for robotic arm

Bratchikov, Sterpan; Abdullin, Artur; **Demidova, Galina**; Lukichev, Dmitry 2021 IEEE 19th International Power Electronics and Motion Control Conference, The Silesian University of Technology Gliwice, Poland, 25 - 29 April, 2021 (PEMC) : proceedings 2021 / p. 717-723 <https://doi.org/10.1109/PEMC48073.2021.9432535>

New stability conditions for discrete polynomials

Nurges, Ülo; Rüstern, Ennu Proceedings of the 2005 American Control Conference : June 8-June 10, 2005, Hilton Portland & Executive Tower, Portland, Oregon. Vol. 6 2005 / p. 4149-4153 : ill
https://folk.ntnu.no/skoge/prost/proceedings/acc05/PDFs/Papers/0742_FrB05_6.pdf

Reflection segments based robust PID controller solution for benchmark problem

Avanessov, Sergei; Nurges, Ülo 2014 22nd Mediterranean Conference on Control and Automation (MED) : University of Palermo, June 16-19, 2014, Palermo, Italy 2014 / p. 1406-1411 : ill

Reflection segments based stability domain approximation of the robust PID controller parameters

Avanessov, Sergei; Nurges, Ülo 2012 20th Mediterranean Conference on Control & Automation (MED), MED 2012 : Conference Proceedings : July 3-6, 2012, Catalonia Barcelona PlazaHotel, Barcelona, Spain 2012 / p. 204-209 : ill
<https://ieeexplore.ieee.org/document/6265639>

Stability of discrete-time systems via polytopes of reflection vector sets

Avanessov, Sergei; Nurges, Ülo Estonian journal of engineering 2012 / p. 291-301