

Underwater map-based localization using flow features

Muhammad, Naveed; Toming, Gert; Tuhtan, Jeffrey A.; Musall, Mark; **Kruusmaa, Maarja** Autonomous robots 2017 / p. 417-436 : ill
<https://doi.org/10.1007/s10514-016-9558-0> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)