

Dynamic pole placement based control of nonlinear discrete time systems with input delay

Belikov, Juri; Petlenkov, Eduard Control Applications (CCA) & Intelligent Control (ISIC) : 2009 IEEE : 8-10 July 2009, St.Petersburg 2009 / p. 394-399

Model reference control of nonlinear TITO systems by dynamic output feedback linearization of neural network based ANARX models

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NN-ANARX model based control of nonlinear discrete-time systems with input delay

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