

Proposal of recovery strategy from loss of leg incident for legged walking robot

Seljanko, Filipp 2012 17th International Conference on Methods and Models in Automation and Robotics (MMAR 2012) : 27-30
August 2012, Miedzydroje, Poland : [proceedings] 2012 / p. 379-384 : ill <https://ieeexplore.ieee.org/abstract/document/6347859>

Thoughts on walking robot for urban search and rescue

Seljanko, Filipp Proceedings of 2012 IEEE International Conference on Mechatronics and Automation : August 5-8, 2012, Chengdu, China 2012 / p. 2411-2416 : ill <https://ieeexplore.ieee.org/document/6285723>

Towards generalized movement strategy for six-legged walking robot

Seljanko, Filipp Info- ja kommunikatsioonitehnoloogia doktorikooli IKTDK viienda aastakonverentsi artiklite kogumik : 25.-26. novembril 2011, Nelijärve 2011 / p. 35-38 : ill

Towards hybrid genetic-gravitational algorithm for control of six-legged walking robot

Seljanko, Filipp Info- ja kommunikatsioonitehnoloogia doktorikooli IKTDK neljanda aastakonverentsi artiklite kogumik : 26.-27. novembril 2010, Essu mõis 2010 / lk. 97-100 : ill