

Biomimetic mechanical design for soft-bodied underwater vehicles

Fiazza, C.; **Salumäe, Taavi**; **Listak, Madis**; Kulikovskis, Guntis; Templeton, R.; Akanyeti, Otar; McGill, W.; Fiorini, Paolo; **Kruusmaa, Maarja** IEEE OCEANS : Sydney, 24-27 May 2010 / [7] p.: ill

Development of a cognitive robotic system for simple surgical tasks

Muradore, Riccardo; Fiorini, Paolo; **Li, Lin**; **Kruusmaa, Maarja**; **Ristolainen, Asko** International journal of advanced robotic systems 2015 / p. 1-20 : ill <https://doi.org/10.5772/60137> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Myometry-driven compliant-body design for underwater propulsion

Akanyeti, Otar; **Listak, Madis**; **Ernits, Andres**; Fiazza, Maria-Camilla; **Toming, Gert**; Kulikovskis, Guntis; **Raag, Rasmus**; **Salumäe, Taavi**; Fiorini, Paolo; **Kruusmaa, Maarja** IEEE International Conference on Robotics and Automation : ICRA 2010 : Anchorage, Alaska, USA, 3-7 May 2010 / p. 84-89 <https://ieeexplore.ieee.org/document/5509431>