

Cyber-physical universal safety and crash detection system for autonomous robot

Pikner, Heiko; Malayjerdi, Mohsen Robotic systems and applications 2021 / p. 46-52 : ill <https://doi.org/10.21595/rsa.2021.22113>

Modular smart control system architecture for the mobile robot platform

Sell, Raivo; Väljaots, Eero; Patariaia, Tengiz; Malayjerdi, Ehsan Proceedings of the Estonian Academy of Sciences 2019 / p. 395-400 : ill http://www.kirj.ee/32713/?tpl=1061&c_tpl=1064 <https://doi.org/10.3176/proc.2019.4.08> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Multi-layer cyber-physical control method for mobile robot safety systems

Pikner, Heiko; Sell, Raivo; Majak, Jüri; Karjust, Kristo Proceedings of the Estonian Academy of Sciences 2021 / p. 383-391 : ill <https://doi.org/10.3176/proc.2021.4.03> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

The mobility of robotised work cells in manufacturing

Vaher, Kristo; **Kangru, Tavo; Otto, Tauno; Riives, Jüri** Proceedings of the 30th International DAAAM Symposium : Intelligent Manufacturing & Automation, 23-26th October 2019, Zadar, Croatia 2019 / p. 1049-1055 : ill <https://doi.org/10.2507/30th.daaam.proceedings.146>

Wheel motion resistance and soil thrust traction of mobile robot

Petritšenko, Andres; Sell, Raivo Proceedings of the 8th International Conference of DAAAM Baltic Industrial Engineering, 19-21st April 2012, Tallinn, Estonia. 1 2012 / p. 332-337 : ill