

Multirate depth control of an AUV by neural network model reference controller for enhanced situational awareness
Astrov, Igor; Gordon, Boris Recent researches in applied information science : proceedings of the 5th WSEAS World Congress on Applied Computing Conference (ACC '12) : proceedings of the 1st International Conference on Biologically Inspired Computation (BIC '12) : University of Algarve, Faro, Portugal, May 2-4, 2012 2012 / p. 32-37 : ill <http://www.wseas.us/e-library/conferences/2012/Algarve/BICA/BICA-04.pdf>

Multirate depth control of an AUV by neural network model reference controller for enhanced situational awareness
[Electronic resource]
Astrov, Igor; Gordon, Boris Proceedings of the International Conferences : Recent Researches in Applied Information Science : [Faro, Portugal, May 2-4, 2012] 2012 / p. 32-37 : ill [CD-ROM] <http://www.wseas.us/e-library/conferences/2012/Algarve/BICA/BICA-04.pdf>

A trajectory control method for a strongly underactuated spherical underwater surveillance robot
Astrov, Igor; Udal, Andres; Mölder, Heigo 2021 IEEE 25th International conference on intelligent engineering systems (INES), 7-9 July 2021 : conference proceedings 2021 / p. 43-48 <https://doi.org/10.1109/INES52918.2021.9512931>