

Multirate depth control of an AUV by neural network model reference controller for enhanced situational awareness

Astrov, Igor; Gordon, Boris Recent researches in applied information science : proceedings of the 5th WSEAS World Congress on Applied Computing Conference (ACC '12) : proceedings of the 1st International Conference on Biologically Inspired Computation (BIC '12) : University of Algarve, Faro, Portugal, May 2-4, 2012 2012 / p. 32-37 : ill <http://www.wseas.us/e-library/conferences/2012/Algarve/BICA/BICA-04.pdf>

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Astrov, Igor; Gordon, Boris Proceedings of the International Conferences : Recent Researches in Applied Information Science : [Faro, Portugal, May 2-4, 2012] 2012 / p. 32-37 : ill [CD-ROM] <http://www.wseas.us/e-library/conferences/2012/Algarve/BICA/BICA-04.pdf>