

Any dynamical system is fully accessible through one singleactuator and related problems

Kawano, Yu; **Kotta, Ülle**; Moog, Claude International journal of robust and nonlinear control 2016 / p. 1748-1754

<http://dx.doi.org/10.1002/rnc.3379>

Event-triggered resilient distributed extended Kalman filter with consensus on estimation

Rezaei, Hossein; **Ghorbani, Majid** International Journal of Robust and Nonlinear Control 2022 / p. 1303 - 1315

<https://doi.org/10.1002/rnc.5881> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Measurement feedback disturbance decoupling in discrete-event systems

Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey International journal of robust and nonlinear control 2015 / p. 3330-3348

<http://dx.doi.org/10.1002/rnc.3265>

Realizations in feedforward forms of nonlinear input-output equations with time-delays

Kaldmäe, Arvo; Kawano, Yu; **Kotta, Ülle** International journal of robust and nonlinear control 2020 / p. 7560-7573

<https://doi.org/10.1002/rnc.5194> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)