

Control of radial increment and winding density of composite cylindrical shells

Kutin, Aleksei; **Arjassov, Gennadi**; **Vu, Trieu Minh**; Musalimov, Victor; Moezzi, Reza; Cyrus, Jindrich MM science journal 2020 / p. 4149–4153 https://doi.org/10.17973/MMSJ.2020_11_2020058 [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Design and experimentation of fuzzy logic control for an anti-lock braking system

Aksjonov, Andrei; **Vodovozov, Valery**; **Petlenkov, Eduard** BEC 2016 : 2016 15th Biennial Baltic Electronics Conference : proceedings of the 15th Biennial Baltic Electronics Conference : Tallinn University of Technology, October 3-5, 2016, Tallinn, Estonia 2016 / p. 207-210 : ill http://www.ester.ee/record=b2150914*est

A model-based adaptive control of an autonomous driving car for lane change maneuver

Astrov, Igor; **Udal, Andres**; **Jaanus, Martin** 2021 44th International Convention on Information, Communication and Electronic Technology (MIPRO), September 27 - October 1, 2021, Opatija, Croatia : proceedings 2021 / p. 1330-1335 : ill <http://www.mipro.hr/LinkClick.aspx?fileticket=RAMnkK6T5UQ%3d&tabid=196&language=hr-HR> <https://doi.org/10.23919/MIPRO52101.2021.9597195>

A model-based adaptive control of turning maneuver for catamaran autonomous surface vessel

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Spatial representation of self-driving vehicle for virtual entity of digital twin

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Wind force model and adaptive control of catamaran model sailboat

Astrov, Igor; **Udal, Andres**; **Mölder, Heigo**; **Jalakas, Tanel**; **Möller, Taavi** 2022 8th International Conference on Automation, Robotics and Applications, ICARA 2022 2022 / p. 202-208 : ill <https://doi.org/10.1109/ICARA55094.2022.9738524>