

Camera-LiDAR fusion based object segmentation in adverse weather conditions for autonomous driving

Gu, Junyi; Bellone, Mauro; Lind, Artjom 2024 19th Biennial Baltic Electronics Conference (BEC) 2024

<https://doi.org/10.1109/BEC61458.2024.10737955> [Conference proceedings at Scopus](#) [Article at Scopus](#) [Article at WOS](#)

CLFT : camera-LiDAR fusion transformer for semantic segmentation in autonomous driving

Gu, Junyi; Bellone, Mauro; Pivonka, Tomas; Sell, Raivo IEEE Transactions on Intelligent Vehicles 2024 / 12 p

<https://doi.org/10.1109/TIV.2024.3454971> [Journal metrics at Scopus](#) [Article at Scopus](#)

CLFT : camera-LiDAR fusion transformer for semantic segmentation in autonomous driving : preprint

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End-to-end multimodal sensor dataset collection framework for autonomous vehicles

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