

Aerial imagery based long-range path planning for unmanned ground vehicle

Hudjakov, Robert; Tamre, Mart 7th International Conference Mechatronics Systems and Materials MSM 2011 : Kaunas, Lithuania, 7-9 July, 2011 : abstracts book and full papers CD 2011 / [7] p

Aerial imagery classification and path planning

Hudjakov, Robert; Tamre, Mart 12th International Symposium "Topical Problems in the Field of Electrical and Power Engineering." Doctoral School of Energy and Geotechnology II : Kuressaare, Estonia, June 11-16, 2012 2012 / p. 147-148 : ill

Aerial imagery terrain classification for long-range autonomous navigation

Hudjakov, Robert; Tamre, Mart Proceedings of International Symposium on Optomechatronic Technologies : ISOT 2009 2009 / p. 88-91 <https://ieeexplore.ieee.org/document/5326104>

Aerial imagery terrain classification for long-range autonomous navigation

Hudjakov, Robert; Tamre, Mart Proceedings of the 7th International Conference of DAAAM Baltic Industrial Engineering : 22-24th April 2010, Tallinn, Estonia. [II] 2010 / p. 530-535 : ill

Comparison of aerial imagery and satellite imagery for autonomous vehicle path planning

Hudjakov, Robert; Tamre, Mart Proceedings of the 8th International Conference of DAAAM Baltic Industrial Engineering, 19-21st April 2012, Tallinn, Estonia. 1 2012 / p. 301-308 : ill

Control of autonomous mobile robots using wireless network and MATLAB

Vu, Trieu Minh; Tamre, Mart; Hudjakov, Robert; Shvarts, Dmitry; Põlder, Ahti; Hiiemaa, Maito; Juurma, Märt Proceedings of the 11th International Conference of DAAAM Baltic Industrial Engineering : 20-22th April 2016, Tallinn, Estonia 2016 / p. 235-240 : ill <http://innomet.ttu.ee/daaam/>

Development of virtual reality interface for remote robot control

Lees, Ülar; Hudjakov, Robert; Tamre, Mart Proceedings of the 9th International Conference of DAAAM Baltic Industrial Engineering, 24-26th April 2014, Tallinn, Estonia 2014 / p. 247-250 : ill

Fully automated tuning of microwave coaxial cavity filters = Mikrolaine-koaksiaalfiltrite täisautomaatne häälestamine

Sekhri, Even 2024 https://www.ester.ee/record=b5685094*est <https://digikogu.taltech.ee/et/Item/38784e65-568e-4dd9-aef9-bb5eec5a2a9c> <https://doi.org/10.23658/taltech.20/2024>

Hyperspectral image band selection using pooling

Liyanage, Dhanushka Chamara; Hudjakov, Robert; Tamre, Mart 15th International Conference Mechatronic Systems and Materials : MSM'2020 : The book of selected, peer reviewed papers presented at the 15th International Conference Mechatronic Systems and Materials MSM'2020, July 1-3, 2020, Bialystok, Poland 2020 <https://doi.org/10.1109/MSM49833.2020.9201714>

Hyperspectral imaging methods improve RGB image semantic segmentation of unstructured terrains

Liyanage, Dhanushka Chamara; Hudjakov, Robert; Tamre, Mart 15th International Conference Mechatronic Systems and Materials : MSM'2020 : The book of selected, peer reviewed papers presented at the 15th International Conference Mechatronic Systems and Materials MSM'2020, July 1-3, 2020, Bialystok, Poland 2020 / 5 p. ill <https://doi.org/10.1109/MSM49833.2020.9201738>

Hyperspectral/multispectral imaging methods for quality control

Liyanage, Dhanushka Chamara; Tamre, Mart; Hudjakov, Robert Handbook of research on new investigations in artificial life, AI, and machine learning 2022 / p. 438-461 <https://doi.org/10.4018/978-1-7998-8686-0.ch017>

Implementation of integrated wireless network and MATLAB system to control autonomous mobile robot

Tamre, Mart; Hudjakov, Robert; Shvarts, Dmitry; Põlder, Ahti; Hiiemaa, Maito; Juurma, Märt International Journal of Innovative Technology and Interdisciplinary Sciences : IJTIS 2018 / p. 18-25 : ill <https://doi.org/10.1515/IJTIS.2018.1.1.18-25>

Long-range navigation for unmanned off-road ground vehicle

Hudjakov, Robert; Tamre, Mart 13th International Symposium "Topical Problems in the Field of Electrical and Power Engineering." Doctoral School of Energy and Geotechnology II : Pärnu, Estonia, January 14-19, 2013 2013 / p. 330-331

Long-range navigation for unmanned off-road ground vehicle = Kaugmaa navigatsioonisüsteem maastikuvõimekusega autonoomsetele liikuritega

Hudjakov, Robert 2012 https://www.ester.ee/record=b2906409*est

Orthophoto classification for UGV path planning using heterogeneous computing

Hudjakov, Robert; Tamre, Mart International journal of advanced robotic systems 2013 / [7] p. : ill <https://doi.org/10.5772/56545> https://www.researchgate.net/publication/269785081_Orthophoto_Classification_for_UGV_Path_Planning_using_Heterogeneous_Computing Journal metrics at Scopus Article at Scopus Journal metrics at WOS Article at WOS

Orthophoto analysis for UGV long-range autonomous navigation

Hudjakov, Robert; Tamre, Mart Estonian journal of engineering 2011 / 1, p. 17-27 : ill

Smart terrain perception using hyperspectral imaging = Hüperspektraal-pilditehnika maastiku nutikaks tajumiseks
Liyanage, Dhanushka Chamara 2021 https://www.eester.ee/record=b5472281*est <https://digikogu.taltech.ee/et/Item/e94dc880-2e42-4203-8ddf-9f26b4b0f301> <https://doi.org/10.23658/taltech.58/2021>