

Camera-LiDAR fusion based object segmentation in adverse weather conditions for autonomous driving

Gu, Junyi; Bellone, Mauro; Lind, Artjom 2024 19th Biennial Baltic Electronics Conference (BEC) 2024

<https://doi.org/10.1109/BEC61458.2024.10737955> [Conference proceedings at Scopus](#) [Article at Scopus](#) [Article at WOS](#)

CLFT : camera-LiDAR fusion transformer for semantic segmentation in autonomous driving

Gu, Junyi; Bellone, Mauro; Pivonka, Tomas; **Sell, Raivo** IEEE Transactions on Intelligent Vehicles 2024 / 12 p

<https://doi.org/10.1109/TIV.2024.3454971>

CLFT : camera-LiDAR fusion transformer for semantic segmentation in autonomous driving : preprint

Gu, Junyi; Bellone, Mauro; Pivonka, Tomas; Sell, Raivo arXiv.org 2024 / 12 p. : ill <https://doi.org/10.48550/arXiv.2404.17793>