

A Novel Vision Transformer for Camera-LiDAR Fusion based Traffic Object Segmentation

Tahves, Toomas; Gu, Junyi; Bellone, Mauro; Sell, Raivo Proceedings of the 17th International Conference on Agents and Artificial Intelligence : Volume 2 2025 / p. 566-573 <https://doi.org/10.5220/0013239000003890>