

A quasi-static approach to optimize the motion of an UGV depending on the track profile

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Comparison of aerial imagery and satellite imagery for autonomous vehicle path planning

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Hyperspectral imaging methods improve RGB image semantic segmentation of unstructured terrains

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Orthophoto classification for UGV path planning using heterogeneous computing

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A systematic review of cutting-edge radar technologies : applications for unmanned ground vehicles (UGVs)

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