

Automatic distribution of local testers for testing distributed systems

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DTRON : a tool for distributed model-based testing of time critical applications

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Human-robot interaction learning using timed automata

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Integration of 'Central' and 'Peripheral' Nervous Systems in Scrub Nurse Robot and Comparison Between 'Voluntary' and 'Reflex' Movements

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Learning timed automata from interaction traces

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Model based continual planning and control framework for assistive robots

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