

A bio-inspired compliant robotic fish : design and experiments

EL Daou, Hadi; Salumäe, Taavi; Toming, Gert; Kruusmaa, Maarja 2012 IEEE International Conference on Robotics and Automation : ICRA : Saint Paul, Minnesota, USA, May 14-18, 2012 / p. 5340-5345 : ill

A bio-mimetic design and control of a fish-like robot using compliant structures

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FILOSE for svenning : a flow sensing bioinspired robot

EL Daou, Hadi; Ježov, Jaas; Jung, David S.; Kruusmaa, Maarja; Listak, Madis; Salumäe, Taavi; Toming, Gert IEEE robotics and automation magazine 2014 / p. 51-62 : ill

Modelling of a biologically inspired robotic fish driven by compliant parts

EL Daou, Hadi; Salumäe, Taavi; Chambers, Lily D.; Megill, William M.; Kruusmaa, Maarja Bioinspiration & biomimetics 2014 / p. 1-11 : ill