

A bio-mimetic design and control of a fish-like robot using compliant structures

EL Daou, Hadi; Salumäe, Taavi; Ristolainen, Asko; Toming, Gert; Listak, Madis; Kruusmaa, Maarja The 15th International Conference on Advanced Robotics : Tallinn, Estonia, June 20-23, 2011 2011 / p. 563-568 : ill

Hydrodynamic optimization of a relative link lengths for a biomimetic robotic fish

Anton, Mart; Listak, Madis The 15th International Conference on Advanced Robotics : Tallinn, Estonia, June 20-23, 2011 2011 / p. 530-535 : ill

Improving area coverage by reversible object pushing

Gavšin, Juri; Kruusmaa, Maarja The 15th International Conference on Advanced Robotics : Tallinn, Estonia, June 20-23, 2011 2011 / p. 415-420 : ill <https://ieeexplore.ieee.org/document/6088579>