

**Automatic products identification method**

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**Camera gimbal performance improvement with spinning-mass mechanical gyroscopes**

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**Comparison of aerial imagery and satellite imagery for autonomous vehicle path planning**

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**Development of movement algorithms for a robot manipulator**

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**Dynamic motion energy efficiency measurement of ground vehicles**

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**Kinematics and dynamics of configurable wheel-leg**

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**Local and global descriptors for place recognition in robotics**

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**Low speed motion feedback for the unmanned ground vehicle**

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**Model validation and structural analysis of a small wind turbine blade**

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**Production machinery utilization monitoring based on acoustic and vibration signal analysis**

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**Wheel motion resistance and soil thrust traction of mobile robot**

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