

Gait analysis based approach for Parkinson's disease modeling with decision tree classifiers

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Thoughts on walking robot for urban search and rescue

Seljanko, Filipp Proceedings of 2012 IEEE International Conference on Mechatronics and Automation : August 5-8, 2012, Chengdu, China 2012 / p. 2411-2416 : ill <https://ieeexplore.ieee.org/document/6285723>