

A method to improve instationary force error estimates for undulatory swimmers

Tuhtan, Jeffrey Andrew; Toming, Gert; Ruuben, Toomas; Kruusmaa, Maarja Underwater technology 2016 / p. 141-151 : ill
<https://doi.org/10.3723/ut.33.141>

Collective responses of a large mackerel school depend on the size and speed of a robotic fish but not on tail motion

Kruusmaa, Maarja; Rieucan, Guillaume; Castillo Montoya, Jose Carlos; Markna, Riho; Handegard, Nils Olav Bioinspiration & biomimetics 2016 / p. 1-12 : ill <http://dx.doi.org/10.1088/1748-3190/11/5/056020>

Experimental study of hydrodynamic forces acting on artificial fish in a von Kármán vortex street

Toming, Gert; Chambers, Lily D.; Kruusmaa, Maarja Underwater technology 2014 / p. 81-91 : ill

Salmon behavioural response to robots in an aquaculture sea cage

Kruusmaa, Maarja; Gkliva, Roza; Tuhtan, Jeffrey Andrew; Tuvikene, A.; Alfredsen, J.A. Royal Society open science 2020 / art. 191220, 14 p. : ill <https://doi.org/10.1098/rsos.191220> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)