

Calculation of optimal design for knee joint smart orthosis

Turchinovich, Nikita; Krokhalova, Nadezhda; Monahov, Yuri; **Sivitski, Alina**; Perepelkina, Svetlana; **Penkov, Igor**; **Arjassov, Gennadi** Proceedings of the 11th International Conference of DAAAM Baltic Industrial Engineering : 20-22th April 2016, Tallinn, Estonia 2016 / p. 214-218 : ill <http://innomet.ttu.ee/daaam/>

Design and implementation of a mechatronic elbow orthosis

Minh, Vu Trieu; **Tamre, Mart**; Safonov, Aleksei; Musalimov, Victor; Kovalenko, Pavel; Monakhov, Iurii Mechatronic Systems and Control 2020 / p. 231 - 238 <https://doi.org/10.2316/J.2020.201-0056> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Design of a wearable mechatronic brace

Vu, Trieu Minh; **Tamre, Mart**; Safonov, Aleksei; Kovalenko, Pavel; Monahov, Juri 17th International Symposium "Topical Problems in the Field of Electrical and Power Engineering". Doctoral school of energy and geotechnology. III : Kuressaare, Estonia, January 15-20, 2018 2018 / p. 9-13 : ill http://ise.elnet.ee/record=b2949854~S2*est

3D-printimise võimalused on meditsiinis piiratud

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Model predictive control for modeling human gait motions assisted by Vicon technology

Vu, Trieu Minh; **Tamre, Mart**; Musalimov, Victor; Kovalenko, Pavel; Rubinshtein, Irina; Ovchinnikov, Ivan; Krcmarik, David; Moezzi, Reza Journal European des systemes automatises 2020 / p. 589-600 <https://doi.org/10.18280/jesa.530501> [Journal metrics at Scopus](#) [Article at Scopus](#)

Modeling human gait based on model predictive control

Ovchinnikov, Ivan; **Vu, Trieu Minh**; Kovalenko, Pavel Proceedings of the 11th International Conference of DAAAM Baltic Industrial Engineering : 20-22th April 2016, Tallinn, Estonia 2016 / p. 185-190 : ill <http://innomet.ttu.ee/daaam/>

Modelling of the human knee joint supported by active orthosis

Musalimov, Victor; Monahov, Juri; **Tamre, Mart**; Rõbak, Dmitri; **Sivitski, Alina**; **Arjassov, Gennadi**; **Penkov, Igor** International journal of applied mechanics and engineering 2018 / p. 107-120 : ill <https://doi.org/10.1515/ijame-2018-0007> [Journal metrics at Scopus](#) [Article at Scopus](#)

Motion modeling of the human lower limb, supported by orthoses

Krokhalova, Nadezhda; Turchinovich, Nikita; Ovchinnikov, Ivan; **Penkov, Igor**; **Arjassov, Gennadi**; Perepelkina, Svetlana; Reznikov, S. Proceedings of the 11th International Conference of DAAAM Baltic Industrial Engineering : 20-22th April 2016, Tallinn, Estonia 2016 / p. 132-136 : ill <http://innomet.ttu.ee/daaam/>

Nutikas ortoos hakkab jälgima oma kandjat

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Taibukad tulevikuortoosid prinditakse täpselt patsiendi kehaosa järgi

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TalTechi 3D prinditud plastist käe- ja seljatoed on õhkuläbilaskvad ning esteetiliselt kaunid [Võrguväljaanne]

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Tehnikaülikool panustab meditsiini: kipsi asemel saavad lapsed lemmikangelase pildiga ortoosi [Võrguväljaanne]

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Моделирование походки человека в среде MATLAB/SIMULINK

Ovchinnikov, Ivan; Kovalenko, Pavel; **Vu, Trieu Minh** Известия высших учебных заведений. Приборостроение = Journal of instrument engineering 2016 / с. 690-694 : ил <http://dx.doi.org/10.17586/0021-3454-2016-59-8-690-694>