

Iterative Learning based feedforward control for Transition of a Biplane-Quadrotor Tailsitter UAS

Raj, Nidhish; **Simha, Ashutosh**; Kothari, Mangal; Abhishek; Banavar, Ravi N. 2020 IEEE International Conference on Robotics and Automation (ICRA), 31 May-31 Aug. 2020, Paris, France : proceedings 2020 / p. 321-327 : ill

<https://doi.org/10.1109/ICRA40945.2020.9196671> [Conference Proceedings at Scopus](#) [Article at Scopus](#) [Article at WOS](#)

Modernisation issues of diesel-electric shunting locomotive power units

Hõimoja, Hardi; Jalakas, Tanel; Rosin, Argo; Rassõlkin, Anton Scientific journal of Riga Technical University. Serija 4, Power and electrical engineering 2010 / p. 57-62 : ill <https://ui.adsabs.harvard.edu/abs/2010SJRP...26...58H/abstract>

A Quasi-dynamic approach for the evaluation of structural response in ship collisions and groundings

Kim, Sang-Jin; **Körgesaar, Mihkel**; Taimuri, Ghalib; Kujala, Pentti; Hirdaris, Spyros Proceedings of the Thirtieth (2020) International Ocean and Polar Engineering Conference Shanghai, China, October 11-16, 2020 2020 / p. 3174–3180 ["Quasi-dynamic approach"](#)

[Conference proceeding at Scopus](#) [Article at Scopus](#)

Маневренность пневмоколесных катков

Putk, Aksel-Johannes Строительные и дорожные машины = Construction and road building machinery 1978 / с. 14-17