

Blended antilock braking system control method for all-wheel drive electric sport utility vehicle

Aksjonov, Andrei; **Vodovozov, Valery**; Augsburg, Klaus; **Petlenkov, Eduard** Electrimacs 2019 : Selected Papers, Vol. 1 2020 / p. 229-241 https://doi.org/10.1007/978-3-030-37161-6_17 [Conference proceeding at Scopus](#) [Article at Scopus](#)

Design and simulation of the robust ABS and ESP fuzzy logic controller on the complex braking maneuvers

Aksjonov, Andrei; Augsburg, Klaus; **Vodovozov, Valery** Applied sciences 2016 / p. 1-18 : ill <http://dx.doi.org/10.3390/app6120382>

Design of regenerative anti-lock braking system controller for 4 in-wheel-motor drive electric vehicle with road surface estimation

Aksjonov, Andrei; **Vodovozov, Valery**; Augsburg, Klaus; **Petlenkov, Eduard** International journal of automotive technology 2018 / p. 727-742 : ill <https://doi.org/10.1007/s12239-018-0070-8> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Hardware-in-the-Loop test of an open loop fuzzy control method for decoupled electro-hydraulic antilock braking system

Aksjonov, Andrei; Ricciardi, Vincenzo; Augsburg, Klaus; **Vodovozov, Valery**; **Petlenkov, Eduard** IEEE transactions on fuzzy systems 2020 / p. 965-975: ill <https://doi.org/10.1109/TFUZZ.2020.2965868> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Trajectory phase-plane method - based analysis of stability and performance of a fuzzy logic controller for an anti-lock braking system

Aksjonov, Andrei; Ricciardi, Vincenzo; **Vodovozov, Valery**; Augsburg, Klaus 2019 IEEE International Conference on Mechatronics (ICM) : proceedings 2019 / p. 602-607 : ill <https://doi.org/10.1109/ICMECH.2019.8722831>