

Cognition through multy-domain practical project

Tamre, Mart; Kask, A.; Sell, Raivo; Leomar, Priit OST-03 Symposium on Machine Design 2003 / p. 278

Control and modelling of rehabilitation process of human leg joints

Tamre, Mart; Leomar, Priit; Puusemp, Raho Mechatronics, robotics and biomechanics 2003 : international conference - March 24-27, 2003, Hrotovice, Czech Republic : proceedings 2003 / p. 179-180

Estonian making steps towards joining international UAV Community

Leomar, Prit; Tamre, Mart; Vaher, Tõnu Proc. of Conf. EURO UAV : 2004, France 2004 / [11] p

Methodologies on the mechatronics domain

Sell, Raivo; Leomar, Priit OST-03 Symposium on Machine Design 2003 / p. 53-59 : ill

Optimal design and analysis of UAV swan fuselage

Leomar, Prit; Tamre, Mart; Riibe, Tõnis; Vaher, Tõnu; Haggi, Toomas Solid state phenomena 2006 / Mechatronic systems and materials, p. 91-96 : ill <https://www.scientific.net/SSP.113.91>

Optimal design and analysis of UAV swan fuselage

Leomar, Prit; Tamre, Mart; Riibe, Tõnis; Vaher, Tõnu; Haggi, Toomas Proceedings of International Conference MSM2005 : Mechatronics Systems and Materials 2005 / ? p <https://www.scientific.net/SSP.113.91>

Simulation of car safety belt operation considering the locking mechanism behaviour

Tamre, Mart; Leomar, Priit; Kulik, D. OST-03 Symposium on Machine Design 2003 / p. 60

Universal navigation algorithm planning platform for unmanned systems

Sell, Raivo; Leomar, Priit Proceedings of International Conference Mechatronic Systems and Materials : Vilnius, Lithuania, 22-25 October 2009 2009 / p. 63-64

https://www.researchgate.net/publication/243762582_Universal_Navigation_Algorithm_Planning_Platform_for_Unmanned_Systems

Universal navigation algorithm planning platform for unmanned systems

Sell, Raivo; Leomar, Priit Mechatronic systems and materials : mechatronic systems and robotics 2010 / p. 405-410 : ill

https://www.researchgate.net/publication/243762582_Universal_Navigation_Algorithm_Planning_Platform_for_Unmanned_Systems