

## Aasta parimad teadusartiklid

Mente et Manu 2023 / lk. 22-25 : fot [https://www.estet.ee/record=b1242496\\*est](https://www.estet.ee/record=b1242496*est)

### Aerial imagery terrain classification for long-range autonomous navigation

Hudjakov, Robert; Tamre, Mart Proceedings of International Symposium on Optomechatronic Technologies : ISOT 2009 2009 / p. 88-91 <https://ieeexplore.ieee.org/document/5326104>

### Aerial imagery terrain classification for long-range autonomous navigation

Hudjakov, Robert; Tamre, Mart Proceedings of the 7th International Conference of DAAAM Baltic Industrial Engineering : 22-24th April 2010, Tallinn, Estonia. [II] 2010 / p. 530-535 : ill

### Applying RIS-based communication for collaborative computing in a swarm of drones

Rahbari, Dadmehr; Alam, Muhammad Mahtab; Le Moullec, Yannick; Jenihhin, Maksim IEEE Access 2023 / p. 70093-70109 <https://doi.org/10.1109/ACCESS.2023.3293737>

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### Cell coverage analysis of a low altitude aerial base station in wind perturbations

Sharma, Navoday; Sharma, Vishal; Magarini, Maurizio; Pervaiz, Haris; Alam, Muhammad Mahtab; Le Moullec, Yannick 2019 IEEE Globecom Workshops (GC Wkshps) : Proceedings 2019 / 6 p <https://doi.org/10.1109/GC Wkshps45667.2019.9024665>

### CITYAM empowers responsible urban air mobility : deliverable of activity 1.5 - setting up the evaluation framework

Müür, Jaanus 2024 <https://interreg-baltic.eu/wp-content/uploads/2024/02/D1.5-Setting-up-the-evaluation-framework-final.pdf>

### Civil liability regime for artificial intelligence : European added value assessment

Evas, Tatjana 2020 [https://www.europarl.europa.eu/RegData/etudes/STUD/2020/654178/EPRS\\_STU\(2020\)654178\\_EN.pdf](https://www.europarl.europa.eu/RegData/etudes/STUD/2020/654178/EPRS_STU(2020)654178_EN.pdf)  
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### Conceptual test bench for small class unmanned autonomous vehicle performance estimation

Pütsep, Kristjan; Rassõlkin, Anton; Vaimann, Toomas 2021 IEEE 19th International Power Electronics and Motion Control Conference, The Silesian University of Technology Gliwice, Poland, 25 - 29 April, 2021 (PEMC) : proceedings 2021 / p. 695-698 : ill  
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### A configurable radio jamming prototype for physical layer attacks against malicious unmanned aerial vehicles

Caforio, Giulio; Scazzoli, Davide; Reggiani, Luca; Magarini, Maurizio; Le Moullec, Yannick; Alam, Muhammad Mahtab 2020 17th Biennial Baltic electronics conference, Tallinn, Estonia, October 6-8, 2020 : proceedings 2020 / 6 p. : ill  
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### Development and testing of vertical take-off and landing aerial vehicle with tandem electric ducted fan motor

Pütsep, Kristjan; Nerep, Tõivo; Tiismus, Hans; Rassõlkin, Anton Proceedings of the Estonian Academy of Sciences 2023 / p. 184–193 <https://doi.org/10.3176/proc.2023.2.08>

### Device-to-device discovery and localization assisted by UAVs in pervasive public safety networks

### **Doktoritöö aitab droone kuulekamaks muuta**

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### **Droon lendab terroriohvreile appi**

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### **Droonid uurivad vihmausside bioindikatsiooni abil raskemetallide levikut keskkonnas**

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### **Droonide lihtsus ja odavus võimaldab neid sõjas massiliselt kasutada [Võrguväljaanne]**

Klementi, Joakim err.ee 2022 [Droonide lihtsus ja odavus võimaldab neid sõjas massiliselt kasutada](https://www.estet.ee/record=b1242496*est)

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### **Eesti kaitsetööstus on kümne aastaga kujunenud tugevaks majandusharuks**

Ränisoo, Tarmo Postimees 2021 / lk. 18-19 : fot <https://dea.digar.ee/article/postimees/2021/02/25/15.2>

### **Eesti teadlaste juhtimisel luuakse droonilahendus terrorirünnaku ohvrite aitamiseks [Võrguväljaanne]**

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### **Ehitustegevuse kaardistamine kaugseirega**

Puust, Raido Horisont 2020 / lk. 49-53 : fot [https://www.estet.ee/record=b1072243\\*est](https://www.estet.ee/record=b1072243*est)

### **Energy consumption of mini UAV helicopters with different number of rotors**

Aleksandrov, Dmitri; Penkov, Igor 11th International Symposium "Topical Problems in the Field of Electrical and Power Engineering." Doctoral School of Energy and Geotechnology II : Pärnu, Estonia, January 16-21, 2012 2012 / p. 259-262 : ill

### **Estonian scientists create a drone solution to help victims of terrorist attacks [Online resource]**

Hankewitz, Sten estonianworld.com 2021 ["Estonian scientists create a drone solution to help victims of terrorist attacks"](#)

### **Fast and fair computation offloading management in a swarm of drones using a rating-based federated learning approach**

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Haddad, Yazeed; Orye, Erwin; Maennel, Olaf Manuel 2021 IEEE International Conference on Cognitive and Computational Aspects of Situation Management (CogSIMA) : Virtual Conference, 14-22 May 2021 : proceedings 2021 / p. 161-166  
<https://doi.org/10.1109/CogSIMA51574.2021.9475928>

### **GPS-i segamisel võib olla mitu põhjust**

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Majd, Amin; Loni, Mohammad; Sahebi, Golnaz; Daneshthalab, Masoud Drones 2020 / art. 48, 19 p. : ill  
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### Internet of drones-enabled Smart Cities

Sharma, Navuday; Magarini, Maurizio; Alam, Muhammad Mahtab IoT Architectures, Models, and Platforms for Smart City Applications 2020 / p. 107-133 <https://doi.org/10.4018/978-1-7998-1253-1.ch006>

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## Robootikafestivalil Robotex käis võistlemas ligi 600 robootikut [Võrguväljaanne]

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## TalTechi teadlased hakkavad NATO toel uudse droonilahendusega terrorirünnakute ohvreid aitama [Võrguväljaanne]

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Reineberg, Lisete Tartu Postimees 2021 / Lk. 4 : fot <https://dea.digar.ee/article/tartupostimees/2021/05/27/7.13>

**VTOL drone with tandem EDF motor and development of an algorithm for automatic stabilization in hover flight**

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**Värske doktoritöö: kuidas juhtida drooni, mis suudab manööverdada igas suunas?**

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**эффективное средство защиты от дронов-камикадзе еще только предстоит найти [Online resources]**

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