

Any dynamical system is fully accessible through one single actuator and related problems

Kawano, Yu; **Kotta, Ülle**; Moog, Claude International journal of robust and nonlinear control 2016 / p. 1748-1754
<https://doi.org/10.1002/rnc.3379> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Event-triggered resilient distributed extended Kalman filter with consensus on estimation

Rezaei, Hossein; **Ghorbani, Majid** International Journal of Robust and Nonlinear Control 2022 / p. 1303 - 1315
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Measurement feedback disturbance decoupling in discrete-event systems

Kaldmäe, Arvo; **Kotta, Ülle**; Shumsky, Alexey; Zhirabok, Alexey International journal of robust and nonlinear control 2015 / p. 3330-3348 <https://doi.org/10.1002/rnc.3265> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Realizations in feedforward forms of nonlinear input-output equations with time-delays

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Robust fractional order singular Kalman filter

Nosrati, Komeil; **Belikov, Juri**; **Teplyakov, Aleksei**; **Petlenkov, Eduard** International journal of robust and nonlinear control 2024 / p. 602-627 : ill <https://doi.org/10.1002/rnc.6990> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)