

Aerial imagery classification and path planning

Hudjakov, Robert; Tamre, Mart 12th International Symposium "Topical Problems in the Field of Electrical and Power Engineering." Doctoral School of Energy and Geotechnology II : Kuressaare, Estonia, June 11-16, 2012 / p. 147-148 : ill

Aerial imagery terrain classification for long-range autonomous navigation

Hudjakov, Robert; **Tamre, Mart** Proceedings of International Symposium on Optomechatronic Technologies : ISOT 2009 2009 / p. 88-91 <https://ieeexplore.ieee.org/document/5326104>

Aerial imagery terrain classification for long-range autonomous navigation

Hudjakov, Robert; Tamre, Mart Proceedings of the 7th International Conference of DAAAM Baltic Industrial Engineering : 22-24th April 2010, Tallinn, Estonia. [II] 2010 / p. 530-535 : ill

Algoritmi õpetab isejuhtiva auto mõõdasõite tegema

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Assisting control algorithms for simplified operation of remotely controlled unmanned ground vehicle

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Calculation of the traction effort of ISEAUTO self-driving vehicle

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Deep learning for radar-based object detection in unmanned ground vehicles

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Energy efficiency evaluation method for mobile robot platform design = Liikuva robotplatvormi energia efektiivsuse hindamise meetod

Väljaots, Eero 2017 <https://digi.lib.ttu.ee/i/?7414> https://www.ester.ee/record=b4665023*est

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Idee : TalTechi Iseauto sobiks lennujaamadesse

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Isejuhtiv buss alustas regulaarsel liinil Kadrirus

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Legged Locomotion on Soft and Wet Terrains [Võrguteavik] = Jalgadel liikumine pehmel ja märjal maastikul

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Modelling and simulation of autonomous vehicles and systems and their advanced control methods = Autonomsete sõidukite ja süsteemide ning nende täiustatud juhtimismetoodikate modelleerimine ja simuleerimine

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Orthophoto classification for UGV path planning using heterogeneous computing

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