

Amfiibrobotid aitavad aimu saada veealusest elust

Traks, Kristina novaator.err.ee 2023 [Amfiibrobotid aitavad aimu saada veealusest elust](#) [Robotid aitavad aimu saada veealusest elust](#)

Development and experimental assessment of a flexible robot fin

Gkliva, Roza; Sfakiotakis, Michael; Kruusmaa, Maarja 2018 IEEE International Conference on Soft Robotics (RoboSoft) : proceedings 2018 / p. 208-213 : ill <https://doi.org/10.1109/ROBOSOFT.2018.8404921>

Dynamic modelling of a screw actuator for improved locomotion control on various terrains

Remmas, Mohamed Walid; Gkliva, Roza; Ristolainen, Asko EGU General Assembly 2022 2022 / EGU22-5726 <https://doi.org/10.5194/egusphere-egu22-5726>

A flapped paddle-fin for improving underwater propulsive efficiency of oscillatory actuation

Simha, Ashutosh; Gkliva, Roza; Kotta, Ülle; Kruusmaa, Maarja IEEE robotics and automation letters 2020 / p. 3176-3181 <https://doi.org/10.1109/LRA.2020.2975747> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Monitoring of coastal waves and velocities with a robotic platform

Piho, Laura; Egerer, Margit; Gkliva, Roza; Kruusmaa, Maarja; Ristolainen, Asko OCEANS 2024 - Halifax : proceedings 2024 / 5 p <https://doi.org/10.1109/OCEANS55160.2024.10754335> [Conference proceedings at Scopus](#) [Article at Scopus](#)

A multi-terrain robot prototype with archimedean screw actuators : design, realization, modeling, and control

Gkliva, Roza; Remmas, Mohamed Walid; Godon, Simon Pierre; Rebane, Jaan; Ochs, Kilian; Kruusmaa, Maarja; Ristolainen, Asko IEEE Access 2024 / p. 95820 - 95830 <https://doi.org/10.1109/ACCESS.2024.3426105> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Novel mechanisms of robot locomotion : variable stiffness actuators for underwater and multi-phase environments =

Robotite uudsed liikumismehhanismid : muutuva jäikusega täituriid veealustes ja mitmefaasilistes keskkondades

Gkliva, Roza 2023 <https://doi.org/10.23658/taltech.3/2023> <https://digikogu.taltech.ee/et/Item/b1135cd8-02a8-44f8-8b2c-d66d019ea63c> https://www.ester.ee/record=b5537817*est

Research: Robots assist in gaining glimpse of life underwater

Traks, Kristina news.err.ee 2023 [Research: Robots assist in gaining glimpse of life underwater](#)

ROBOMINERS resilient reflectance/fluorescence spectrometers

Burlet, Christian; Stasi, Giorgia; Godon, Simon Pierre; Gkliva, Roza; Piho, Laura; Ristolainen, Asko EGU General Assembly 2023, Vienna, Austria, 24–28 Apr 2023 2023 / EGU-12056 <https://doi.org/10.5194/egusphere-egu23-12056>

Salmon behavioural response to robots in an aquaculture sea cage

Kruusmaa, Maarja; Gkliva, Roza; Tuhtan, Jeffrey Andrew; Tuvikene, A.; Alfredsen, J.A. Royal Society open science 2020 / art. 191220, 14 p. : ill <https://doi.org/10.1098/rsos.191220> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Soft fluidic actuator for locomotion in multi-phase environments

Gkliva, Roza; Kruusmaa, Maarja IEEE robotics and automation letters 2022 / p. 10462-10469 <https://doi.org/10.1109/LRA.2022.3192204> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Whisker-based tactile navigation algorithm for underground robots

Kossas, Tanel; Remmas, Mohamed Walid; Gkliva, Roza; Ristolainen, Asko; Kruusmaa, Maarja 2024 IEEE International Conference on Robotics and Automation (ICRA) 2024 / p. 13164-13170 <https://doi.org/10.1109/ICRA57147.2024.10610762> [Conference proceedings at Scopus](#) [Article at Scopus](#) [Article at WOS](#)