

Digital Twin : universal user interface for online management of the manufacturing system

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Digital twin of an electrical motor based on empirical performance model

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Industrial collaborative robot digital twin integration and control using robot operating system

Diachenko, Danyl; Partyshev, Andriy; Pizzagalli, Simone Luca; Bondarenko, Yevhen; Otto, Tauno; Kuts, Vladimir Journal of Machine Engineering 2022 / p. 57 - 67 <https://doi.org/10.36897/jme/148110> [Journal metrics at Scopus](#) [Article at Scopus](#)

Interface development for digital twin of an electric motor based on empirical performance model

Rassölkin, Anton; Rjabtšikov, Viktor; Kuts, Vladimir; Vaimann, Toomas; Kallaste, Ants; Asad, Bilal; Partyshev, Andriy IEEE Access 2022 / p. 15635-15643 <https://doi.org/10.1109/ACCESS.2022.3148708> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Parametric digital twin of autonomous electric vehicle transmission

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ROS middle-layer integration to Unity 3D as an interface option for propulsion drive simulations of autonomous vehicles

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