

State estimation and control for small low-cost autonomous underwater vehicles = Meetodid olekute hindamiseks ja juhtimiseks soodsa hinnaga autonoomsetele allveerobotitele

Meurer, Christian 2021 https://www.ester.ee/record=b5435482*est <https://digikogu.taltech.ee/et/Item/717111f2-51e3-4176-b0b8-b369064b26a2> <https://doi.org/10.23658/taltech.27/2021>