

A distributed model of ionomeric polymer metal composite

Punning, Andres; Johanson, Urmas; Anton, Mart; Aabloo, Alvo; **Kruusmaa, Maarja** Journal of intelligent material systems and structures 2009 / p. 1711-1724 : ill <https://doi.org/10.1177/1045389X0933717>

Hydrodynamic optimization of a relative link lengths for a biomimetic robotic fish

Anton, Mart; Listak, Madis The 15th International Conference on Advanced Robotics : Tallinn, Estonia, June 20-23, 2011 2011 / p. 530-535 : ill

Linear modeling of elongated bending EAP actuator at large deformations

Must, Indrek; Anton, Mart; **Kruusmaa, Maarja**; Aabloo, Alvo Proceedings of SPIE 2009 / Electroactive Polymer Actuators and Devices (EAPAD) 2009, p. 728723-1 - 728723-12 : ill
https://www.researchgate.net/publication/236115802_Linear_modeling_of_elongated_bending_EAP_actuator_at_large_deformations

A linked manipulator with ion-polymer metal composite (IPMC) joints for soft- and micromanipulation

Kruusmaa, Maarja; Hunt, Andres; Punning, Andres; Anton, Mart; Aabloo, Alvo 2008 IEEE International Conference on Robotics and Automation : Pasadena, CA, 19-23 May 2008. Vols. 1-9 2008 / p. 3588-3593

Mechanoelectrical impedance of a carbide-derived carbon-based laminate motion sensor at large bending deflections

Must, Indrek; **Anton, Mart**; Viidalepp, Erki; Põldsalu, Inga; Punning, Andres; Aabloo, Alvo Smart Materials and Structures 2013 / art. 104015 <https://doi.org/10.1088/0964-1726/22/10/104015> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Towards a biomimetic EAP robot

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