

Depth controls of an autonomous underwater vehicle by neurocontrollers for enhanced situational awareness

Astrov, Igor; Pedai, Andrus Proceedings of the World Academy of Science, Engineering and Technology 2009 / 55, p. 486-489

Flight control of a trirotor mini-UAV for enhanced situational awareness

Astrov, Igor; Pedai, Andrus Proceedings of the World Academy of Science, Engineering and Technology 2010 / p. 271-277 : ill

Multirate neural control for AUV's increased situational awareness during diving tasks using stochastic model

Astrov, Igor; Pedai, Andrus Proceedings of the World Academy of Science, Engineering and Technology 2010 / p. 337-343 : ill