

Bioinspired whisker sensor for 3D mapping of underground mining environments

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Contributions to the modelling and control of fin-actuated autonomous underwater vehicles = Uimedega autonoomsete allveesõidukite modelleerimis- ja juhtimisloogika edendamine

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A multi-terrain robot prototype with archimedean screw actuators : design, realization, modeling, and control

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