

A finite feedback linearization algorithm for nonlinear control systems

Kaldmäe, Arvo Proceedings of the 8th Annual Conference of the Estonian National Doctoral School in Information and Communication Technologies : December 5-6, 2014, Rakvere 2014 / p. 53-56

A tool for advanced learning of LFSR-based testing principles

Jutman, Artur; Tšertov, Anton; Ubar, Raimund-Johannes BEC 2006 : 2006 International Baltic Electronics Conference : Tallinn University of Technology, October 2-4, 2006, Tallinn, Estonia : proceedings of the 10th Biennial Baltic Electronics Conference 2006 / p. 175-178 : ill

Application of neural networks based ANARX structure to backing up control of a truck-trailer [Electronic resource]

Belikov, Juri; Petlenkov, Eduard; Nõmm, Sven 6th IFAC Symposium on Intelligent Autonomous Vehicles : IFAC IAV 2007 : September 3-5, 2007, Toulouse, France : symposium proceedings CD ROM 2007 / [5] p. [CD-ROM]
<https://www.sciencedirect.com/science/article/pii/S147466701634647X>

Calculation of LFSR seed and polynomial pair for BIST applications

Jutman, Artur; Tšertov, Anton; Ubar, Raimund-Johannes Info- ja kommunikatsioonitehnoloogia doktorikooli IKTDK kolmanda aastakonverentsi artiklite kogumik : 25.-26. aprill 2008, Voore külalistemaja 2008 / p. 105-108 : ill

Disturbance decoupling by measurement feedback : sensor location

Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey Proceedings of the Estonian Academy of Sciences 2016 / p. 317-329 : ill <http://dx.doi.org/10.3176/proc.2016.4.05> https://artiklid.elnet.ee/record=b2808632*est

Disturbance decoupling in nonlinear hybrid systems

Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey Nonlinear analysis : hybrid systems 2018 / p. 42-53
<https://doi.org/10.1016/j.nahs.2017.11.001> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Disturbance decoupling in nonlinear hybrid systems [Electronic resource]

Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey 12th IEEE International Conference on Control and Automation : ICCA 2016 : Kathmandu, Nepal, 1-3 June 2016 2016 / p. 86-91 : ill. [USB] <https://doi.org/10.1109/ICCA.2016.7505257>

Disturbance decoupling problem in finite automata : sensor location problem

Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey 2016 IEEE Conference on Control Applications (CCA) : part of 2016 IEEE Multi-Conference on Systems and Control, September 19-22, 2016, Buenos Aires, Argentina 2016 / p. 481-486 : ill <https://doi.org/10.1109/CCA.2016.7587876>

"... ehk juhtimine ja side õppuris ning masinas"

Kukk, Vello E-õppe uudiskiri 2011 / lk. 20-21 <https://uudiskiri.e-ope.ee/2011/03/22/ehk-juhtimine-ja-side-oppuris-ning-masinas/>

Experimental validation of the Newton observer for a nonlinear flux-controlled AMB system operated with zero-bias flux

Mystkowski, Arkadiusz; Kierdelewicz, A.; **Kotta, Ülle; Kaparin, Vadim** International journal of control 2020 / p. 2257-2266 : ill
<https://doi.org/10.1080/00207179.2018.1552025> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Feedback linearization and lattice theory

Kotta, Ülle; Tönsö, Maris; Shumsky, Alexey Ye.; Zhirabok, Alexey N. Systems & control letters 2013 / p. 248-255

Feedback linearization of an active magnetic bearing system operated with a zero-bias flux

Mystkowski, Arkadiusz; **Kaparin, Vadim; Kotta, Ülle; Pawluszewicz, Ewa; Tönsö, Maris** International journal of applied mathematics and computer science 2017 / p. 539-548 : ill <https://doi.org/10.1515/amcs-2017-0038>

Feedback linearization of possibly non-smooth systems

Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey Proceedings of the Estonian Academy of Sciences 2017 / p. 109-123 <https://doi.org/10.3176/proc.2017.2.01> http://www.estet.ee/record=b2355998*est

Fractional order sliding mode controller based on supervised machine learning techniques for speed control of PMSM

Zahraoui, Younes; Zaihidee, Fardila M.; Kermadi, Mostefa; Mekhilef, Saad; Mubin, Marizan; Tang, Jing Rui; Zaihidee, Ezrinda M. Mathematics 2023 / art. 1457 <https://doi.org/10.3390/math11061457>

Hierarchical temporal memory implementation on FPGA using LFSR based spatial pooler

Kerner, Madis; **Tammemäe, Kalle** Proceedings 2017 IEEE 20th International Symposium on Design and Diagnostics of Electronic Circuit & Systems(DDECS) : April 19-21, 2017, Dresden, Germany 2017 / p. 92-95 <https://ieeexplore.ieee.org/stamp/stamp.jsp?tp=&arnumber=7934553>

Kompeaistingu kasutamine arvuti sisend-väljundliideses

Joasoon, Erkki; **Henno, Jaak** A & A 2010 / 4, lk. 16-26 : ill https://artiklid.elnet.ee/record=b2286474*est

Measurement feedback disturbance decoupling in discrete-event systems
Kaldmäe, Arvo; Kotta, Ülle; Shumsky, Alexey; Zhirabok, Alexey International journal of robust and nonlinear control 2015 / p. 3330-3348 <http://dx.doi.org/10.1002/rnc.3265>

Minimal realizations of nonlinear time-delay systems
Kaldmäe, Arvo; Zbigniew, Bartosiewicz; Kotta, Ülle; Wyrwas, Małgorzata IEEE transactions on automatic control 2023 / 7 p <https://doi.org/10.1109/TAC.2023.3240124>

Model reference control of nonlinear MIMO systems by dynamic output feedback linearization of ANARX models
Belikov, Juri; Petlenkov, Eduard IEEE International Conference on Control and Automation : ICCA 2009 : Christchurch, New Zealand, December 9-11, 2009 2009 / p. 536-541 <https://ieeexplore.ieee.org/document/5410177?tp=&arnumber=5410177>

Model reference control of nonlinear TITO systems by dynamic output feedback linearization of neural network based ANARX models
Belikov, Juri; Petlenkov, Eduard Control Applications (CCA) & Intelligent Control (ISIC) : 2009 IEEE : 8-10 July 2009, St.Petersburg 2009 / p. 1820-1825 <https://ieeexplore.ieee.org/document/5410177?tp=&arnumber=5410177>

Newton observer for a nonlinear flux-controlled AMB system
Mystkowski, Arkadiusz; Kotta, Ülle; Kaparin, Vadim Proceedings of the Estonian Academy of Sciences 2018 / p. 61-72 : ill <https://doi.org/10.3176/proc.2018.1.03> http://www.esther.ee/record=b2355998*est Journal metrics at Scopus Article at Scopus Journal metrics at WOS Article at WOS

NN-ANARX model based control of nonlinear discrete-time systems with input delay
Belikov, Juri; Petlenkov, Eduard Control Applications (CCA) & Intelligent Control (ISIC) : 2009 IEEE : 8-10 July 2009, St.Petersburg 2009 / p. 1039-1044 <https://ieeexplore.ieee.org/document/5281182>

NN-SANARX model based control of a multi tank liquid-level system
Belikov, Juri; Petlenkov, Eduard International journal of computational intelligence systems 2015 / p. 265-277 <http://dx.doi.org/10.1080/18756891.2015.1001950>

Optimal tuning of fractional order sliding mode controller for PMSM speed using neural network with reinforcement learning
Zahraoui, Younes; Zaihidee, Fardila M.; Kermadi, Mostefa; Mekhilef, Saad; Alhamrouni, Ibrahim; Seyedmahmoudian, Mehdi; Stojcevski, Alex Energies 2023 / art. 4353 <https://doi.org/10.3390/en16114353>

Stability and stabilizability of linear time-delay systems on homogeneous time scales
Belikov, Juri; Bartosiewicz, Zbigniew Proceedings of the Estonian Academy of Sciences 2017 / p. 124-136 <https://doi.org/10.3176/proc.2017.2.02> http://www.esther.ee/record=b2355998*est

State feedback linearization of nonlinear control systems on homogeneous time scales
Bartosiewicz, Zbigniew; Belikov, Juri; Kotta, Ülle; Wyrwas, Małgorzata Nonlinear analysis: hybrid systems 2019 / p. 69-85 <https://doi.org/10.1016/j.nahs.2018.08.002> Journal metrics at Scopus Article at Scopus Journal metrics at WOS Article at WOS

Static state feedback linearization of nonlinear control systems on homogeneous time scales
Bartosiewicz, Zbigniew; Kotta, Ülle; Tõnso, Maris; Wyrwas, Małgorzata Mathematics of control, signals, and systems 2015 / p. 523-550 <http://dx.doi.org/10.1007/s00498-015-0150-5>

The tactile feedback device for multi-touch user interfaces = Kompeaistingul põhineva tagasisidega seade multipuutelise kasutajaliidese jaoks
Joasoon, Erkki 2010 https://www.esther.ee/record=b2607114*est

Using Tabu Search for optimization of memory-constrained hybrid BIST
Kruus, Helena; Jervan, Gert; Ubar, Raimund-Johannes Info- ja kommunikatsioonitehnoloogia doktorikooli IKTDK kolmanda aastakonverentsi artiklite kogumik : 25.-26. aprill 2008, Voore külalistemaja 2008 / p. 85-88 : ill

Метод расчета усилителей с обратной связью
Sillamaa, Hanno Труды по электротехнике и автоматике : сборник статей. 6 1968 / с. 33-43 : илл https://www.esther.ee/record=b2182221*est <https://digikogu.taltech.ee/et/item/28a82977-89e1-4d6c-ae22-51bd6ba069c0>

Сложивающие фильтры с равноволновой переходной характеристикой
Parve, Toomas; Min, Mart Избирательные системы с обратной связью : межвузовский тематический научный сборник 1983 / с. 52-55 https://www.esther.ee/record=b2347952*est

Статика электропривода по системе МУ-Д с электрическим суммированием обратной связи по току
Davõdov, Igor Труды по электротехнике и автоматике : сборник статей. 9 1971 / с. 111-119 : илл https://www.esther.ee/record=b2190156*est <https://digikogu.taltech.ee/et/item/945ec07e-d7b0-466e-bc24-6ad904a829e9/>

Электромагнитное суммирование обратной связи по току в электроприводе по системе МУ-Д

Davõdov, Igor Электромеханика. 4 1973 / с. 27-33 : илл https://www.esther.ee/record=b2190554*est

<https://digikogu.taltech.ee/et/item/a0f6e008-859b-40f0-b091-f60425ec49d5>