

Design and testing of an universal autonomous surface vehicle

Roasto, Indrek; Jalakas, Tanel; Mölder, Heigo; Möller, Taavi; Tabri, Kristjan; Enok, Mart 2021 IEEE 19th International Power Electronics and Motion Control Conference, The Silesian University of Technology Gliwice, Poland, 25 - 29 April, 2021 (PEMC) : proceedings 2021 / p. 705-710 : ill <https://doi.org/10.1109/PEMC48073.2021.9432567>

Motion control of an autonomous surface vessel for enhanced situational awareness

Astrov, Igor; Pikkov, Mihhail; Paluoja, Rein World Academy of Science, Engineering and Technology. International journal of mechanical, industrial science and engineering 2013 / p. 1203-1208 : ill

An optimal control method for an autonomous surface vessel for environment monitoring and cargo transportation applications

Astrov, Igor; Udal, Andres; Mölder, Heigo 2021 25th International Conference Electronics : Proceedings of the 25th International Conference : ELECTRONICS 2021, Kaunas University of Technology, 14th–16th June, 2021, Palanga, Lithuania 2021 / 6 p <https://doi.org/10.1109/IEEECONF52705.2021.9467483>

Simulink/MATLAB based comparison of neural and basic tracking control for an autonomous surface vessel for situation awareness applications

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Target tracking by neural predictive control of autonomous surface vessel for environment monitoring and cargo transportation applications

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