

An integrated electroactive polymer sensor-actuator : design, model-based control, and performance characterization

Hunt, Andres; Chen, Zheng; Tan, K.; Kruusmaa, Maarja Smart materials and structures 2016 / art. 035016, p. 1-16 : ill

<https://doi.org/10.1088/0964-1726/25/3/035016> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Application-oriented performance characterization of the ionic polymer transducers (IPTs) = loonpolümeeridest täiturite võimekuse karakteriseerimine rakendusteks

Hunt, Andres 2017 <https://digi.lib.ttu.ee/i/?7576> https://www.eester.ee/record=b4670806*est

Control of an inverted pendulum using an ionic polymer-metal composite actuator

Hunt, Andres; Chen, Zheng; Tan, Xiaobo; Kruusmaa, Maarja IEEE/ASME Transactions in Mechatronics : 2010 IEEE/ASME

International Conference on Advanced Intelligent Mechatronics : July 6-9, 2010, Montréal, Canada 2010 / p. 163-168 : ill

<https://ieeexplore.ieee.org/document/5695913>

Development of high fidelity liver and kidney phantom organs for use with robotic surgical systems

Õpik, Rivo; Hunt, Andres; Ristolainen, Asko; Aubin, Patrick M.; Kruusmaa, Maarja Proceedings of the 4th IEEE RAS & EMBS International Conference on Biomedical Robotics and Biomechatronics (BioRob), 24-27 June 2012, Rome, Italy 2012 / p. 425-430 : ill

<https://ieeexplore.ieee.org/document/6290831>

Feedback control of a coupled IPMC (Ionic Polymer-Metal Composite) sensor-actuator

Hunt, Andres; Tan, Xiaobo; Chen, Zheng; Kruusmaa, Maarja Proceedings of ASME Dynamic Systems Control Conference :

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A linked manipulator with ion-polymer metal composite (IPMC) joints for soft- and micromanipulation

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Low cost anatomically realistic renal biopsy phantoms for interventional radiology trainees

Hunt, Andres; Ristolainen, Asko; Ross, Peeter; Õpik, Rivo; Krumme, Andres; Kruusmaa, Maarja European journal of radiology 2013 / p. 594-600 : ill

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