

Cost-effective optimization of load shifting in the industry by using intermediate storages

Uemaa, Priit; Kilter, Jako; Valtin, Juhan; Drovtar, Imre; Rosin, Argo; Puusepp, Andres Conference proceedings of IEEE ISGT Europe 2013 : 4th IEEE/PES Innovative Smart Grid Technologies Europe 2013 / [5] p

Covering algorithms for a robot swarm with limited information = Katvusalgorithmid piiratud teadmusbaasiga robotiparvede jaoks

Puusepp, Andres 2017 <https://digi.lib.ttu.ee/?9124> https://www.ester.ee/record=b4694737*est

Covering an unknown area with an RFID-enabled robot swarm

Puusepp, Andres; Tammet, Tanel; Reilent, Enar Mechanical design and power engineering 2014 / p. 1157-1162

RFID-based communications for a self-organizing robot swarm

Tammet, Tanel; Vain, Jüri; Puusepp, Andres; Reilent, Enar; Kuusik, Alar SASO 2008 : Second IEEE International Conference on Self-Adaptive and Self-Organizing Systems : 20-24 October, 2008, Venice, Italy : proceedings 2008 / p. 45-54
<https://ieeexplore.ieee.org/document/4663409>

Robot movement strategies in the environment enriched with RFID tags

Puusepp, Andres; Tammet, Tanel; Puju, Madis; Reilent, Enar 2012 International Conference on System Theory, Control and Computing (ICSTCC) : joint conference SINTES 16, SACCs 12, SIMSIS 16 : proceedings : October 12-14, 2012, Sinaia, Romania 2012 / [6] p. : ill <https://ieeexplore.ieee.org/document/6379287>