Model reference control of nonlinear systems by dynamic output feedback linearization of neural network based ANARX models

Petlenkov, Eduard Proceedings of the 10th International Conference on Control Automation Robotics & Vision (ICARCV 2008): Hanoi, Vietnam, December 17-20, 2008 2008 / p. 1119-1123 https://ieeexplore.ieee.org/document/4795677