

Model reference control of nonlinear MIMO systems by dynamic output feedback linearization of ANARX models
Belikov, Juri; Petlenkov, Eduard IEEE International Conference on Control and Automation : ICCA 2009 : Christchurch, New Zealand, December 9-11, 2009 2009 / p. 536-541 <https://ieeexplore.ieee.org/document/5410177?tp=&arnumber=5410177>

Neural network based dynamic pole placement control of nonlinear systems
Petlenkov, Eduard; Belikov, Juri IEEE International Conference on Control and Automation : ICCA 2009 : Christchurch, New Zealand, December 9-11, 2009 2009 / p. 410-415 <https://ieeexplore.ieee.org/document/5410160>

Reflection coefficient approach to robust state controller design
Nurges, Ülo; Rüstern, Ennu IEEE International Conference on Control and Automation : ICCA 2009 : Christchurch, New Zealand, December 9-11, 2009 2009 / p. 519-523 <https://ieeexplore.ieee.org/document/5410189>

Supervised training of voting automata for the surgeon's motion recognition during laparoscope surgery
Vain, Jüri; Nömm, Sven; Anier, Aivo; Miyawaki, Fujio; Totskaya, Tatiana IEEE International Conference on Control and Automation : ICCA 2009 : Christchurch, New Zealand, December 9-11, 2009 2009 / p. 1503-1508