

Data fusion for ITS : a systematic literature review

Ounoughi, Chahinez; Ben Yahia, Sadok Information Fusion 2023 / p. 267-291 <https://doi.org/10.1016/j.inffus.2022.08.016> [Journal metrics at Scopus](#) [Article at scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

End-to-end multimodal sensor dataset collection framework for autonomous vehicles

Gu, Junyi; Lind, Artjom; Chhetri, Tek Raj; Bellone, Mauro; Sell, Raivo Sensors 2023 / art. 6783, 25 p. : ill <https://doi.org/10.3390/s23156783> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

From sensors to Dempster-Shafer theory and back : the axiom of ambiguous sensor correctness and its applications

Draheim, Dirk; Tammet, Tanel Database and Expert Systems Applications : 31st International Conference, DEXA 2020, Bratislava, Slovakia, September 14–17, 2020 : Proceedings, Part I 2020 / p. 3-19 https://doi.org/10.1007/978-3-030-59003-1_1 [Conference proceedings at Scopus](#) [Article at Scopus](#) [Conference proceedings at WOS](#) [Article at WOS](#)

Lidar-camera semi-supervised learning for semantic segmentation

Caltagirone, Luka; Bellone, Mauro; Svensson, Lennart; Wahde, Mattias; Sell, Raivo Sensors 2021 / art. 4813 <https://doi.org/10.3390/s21144813> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Method for data collection and integration into 3D architectural model

Kurik, Lembit; Sinivee, Veljo; Lints, Martin; Kallavus, Urve Innovations and advances in computer, information, systems sciences, and engineering 2013 / p. 707-717 : ill https://doi.org/10.1007/978-1-4614-3535-8_59 [Article collection metrics at Scopus](#) [Article at Scopus](#)

Method for data collection and integration into 3D architectural model [Electronic resource]

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A Novel Vision Transformer for Camera-LiDAR Fusion based Traffic Object Segmentation

Tahves, Toomas; Gu, Junyi; Bellone, Mauro; Sell, Raivo Proceedings of the 17th International Conference on Agents and Artificial Intelligence : Volume 2 2025 / p. 566-573 <https://doi.org/10.5220/0013239000003890>

Real-time multi-modal active vision for object detection on UAVs equipped with limited field of view LiDAR and camera

Shi, Chuanbeibei; Lai, Ganghua; Yu, Yushu; Bellone, Mauro; Lippiello, Vincezo IEEE Robotics and Automation Letters 2023 / p. 6571 - 6578 <https://doi.org/10.1109/LRA.2023.3309575> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Sensor-location-specific joint acquisition of peripheral artery bioimpedance and photoplethysmogram for wearable applications

Metshein, Margus; Abdullayev, Anar; Gautier, Antoine; Larras, Benoit; Frappe, Antoine; Cardiff, Barry; Annus, Paul; Land, Raul; Märten, Olev Sensors 2023 / art. 7111 <https://doi.org/10.3390/s23167111> [Journal metrics at Scopus](#) [Article at Scopus](#) [Journal metrics at WOS](#) [Article at WOS](#)

Tight coupling of GNSS and IMU using extended Kalman filtering

Babri, Usman Muhammad; Irfan Haider Jillani, Muhammad; Ahmad, Rizwan; Alam, Muhammad Mahtab 19th Biennial Baltic Electronics Conference (BEC) 2024 / 6 p <https://doi.org/10.1109/BEC61458.2024.10737945> [Conference proceedings at Scopus](#) [Article at Scopus](#) [Article at WOS](#)

2D estimation of velocity relative to water and tidal currents based on differential pressure for autonomous underwater vehicles

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UWB and GNSS Sensor Fusion Using ML-Based Positioning Uncertainty Estimation

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